

**CASE STUDY** 

# Shaip's LiDAR Annotation Project for SmartCity Autonomous Vehicles

## **Project Background**

SmartCity, a rapidly growing metropolitan area, initiated an ambitious project to introduce autonomous vehicles (AVs) for public transportation. To ensure safe and efficient operation of these AVs, they needed a vast amount of accurately annotated LiDAR and camera data representing the city's diverse environments. SmartCity partnered with Shaip, a leading data annotation company, to handle this crucial task.

# **Project Overview**

Shaip was tasked with annotating 15,000 frames of sensor data collected from SmartCity's streets. Each frame contained data from 3 Velodyne VLP-32C LiDARs and 4 high-resolution cameras, capturing a wide range of urban scenarios.

## **Challenges**



**Volume and Complexity:** The sheer amount of data and the requirement for both 2D and 3D annotations presented a significant challenge.



Diverse Environments: SmartCity's varied landscape, from dense urban centers to suburban areas, required adaptable annotation strategies.



Consistency: Maintaining consistent object IDs across different sensors and multiple frames was crucial for training reliable Al models.



Privacy Concerns: Ensuring all personal identifiable information was properly masked while preserving useful data.



Tight Timeline: SmartCity needed the project completed within 4 months to meet their AV deployment schedule.

## **Shaip's Approach**



**Staffing:** Assembled a team of 50 experienced annotators, 10 quality controllers, and 3 project managers.



Custom Tools: Developed proprietary software that integrated 2D and 3D annotation workflows, enhancing efficiency and consistency.



Training: Conducted intensive training sessions on SmartCity's specific annotation requirements and privacy guidelines.



**Workflow:** Implemented a multi-stage annotation process with built-in quality checks at each stage.



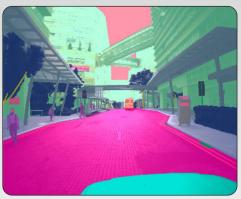
**Automation:** Utilized Al-assisted pre-annotation to speed up the process, especially for common objects like cars and pedestrians.



**Camera Raw Data** 



**Camera Bounding Box Data** 



**Camera Segmented Data** 



**Point Cloud Raw Data** 



**Point Cloud Cuboid Data** 



**Point Cloud Segmented Data** 

#### **Outcome**

- Completed the project in **3.5 months**, two weeks ahead of schedule.
- Achieved 99.7% annotation accuracy, exceeding SmartCity's expectations.
- Successfully annotated over **450,000** unique objects across all frames.
- Maintained consistent IDs for 98% of objects across multiple frames.
- Properly masked all license plates and faces, ensuring privacy compliance.

### **Customer Testimonial**

The high-quality annotated data allowed SmartCity to train their AV systems more effectively, reducing the time needed for real-world testing by 30%. The consistent and accurate annotations particularly improved the AVs' object tracking and prediction capabilities in complex urban environments. \*\*\*\*

#### Conclusion

Shaip's successful execution of this large-scale LiDAR annotation project played a pivotal role in SmartCity's autonomous vehicle initiative. The project demonstrated the importance of combining skilled human annotators with advanced Al-assisted tools to handle complex, multi-sensor data annotation tasks efficiently and accurately.



